

# Measurement of large angle muon flux in GRAPES-3 experiment using triggerless DAQ system

B. Hariharan, GRAPES-3, TIFR  
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# The GRAPES-3 Experiment, Cosmic Ray Laboratory, Ooty

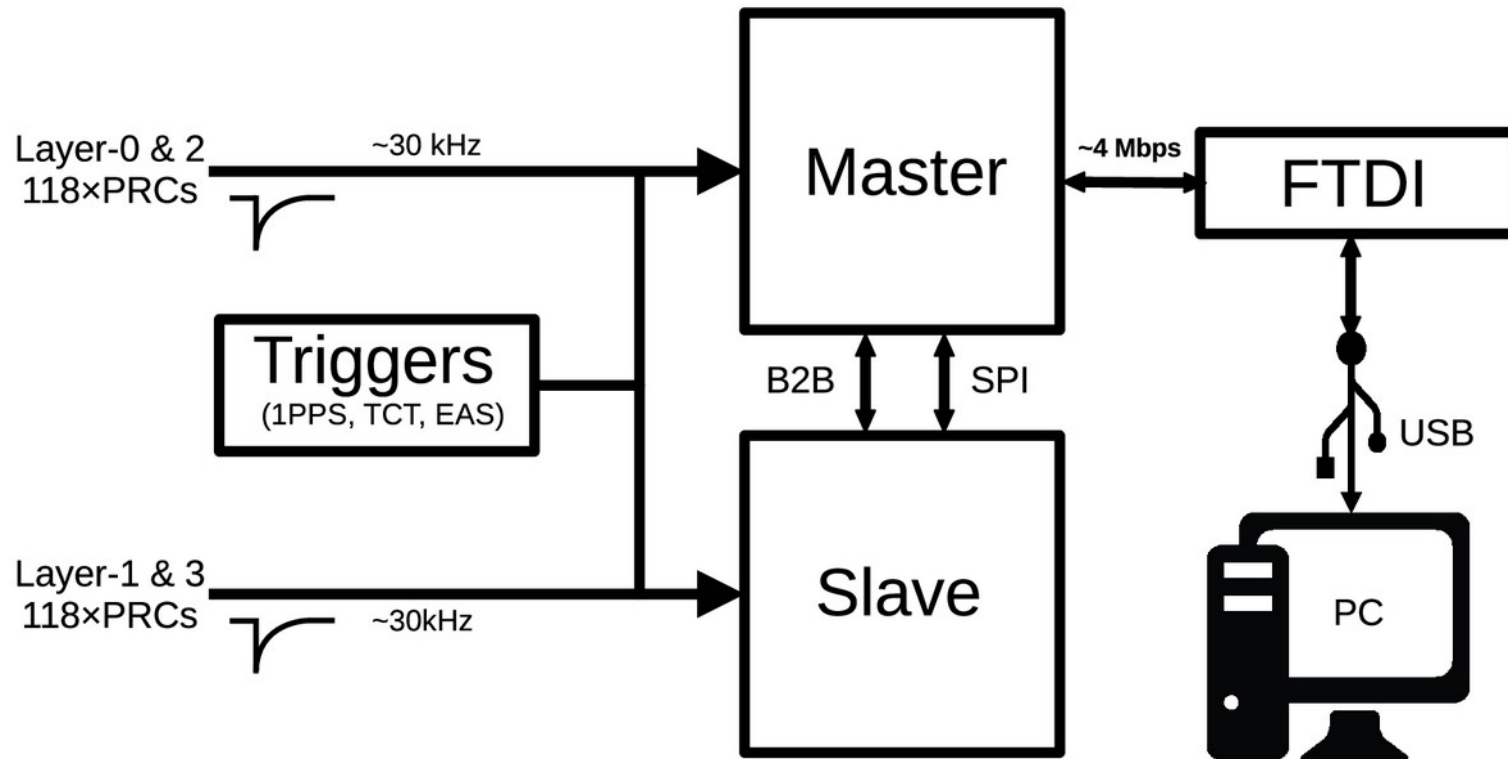
## Muon Telescope

- 3712 PRCs
- 16 Modules
- Area 560 m<sup>2</sup>
- 169 Directions
- $\text{Sec}(\theta)$  GeV
- 4 billion muons/day
- 40-50 events/year

# Conventional DAQ

- Decades old electronics
- Independent DAQs
  - EAS muon component
  - Angular muon flux
- Limited information
- Angular coverage  $< 45^\circ$
- Dead time  $\sim 12\%$

# The new triggerless DAQ

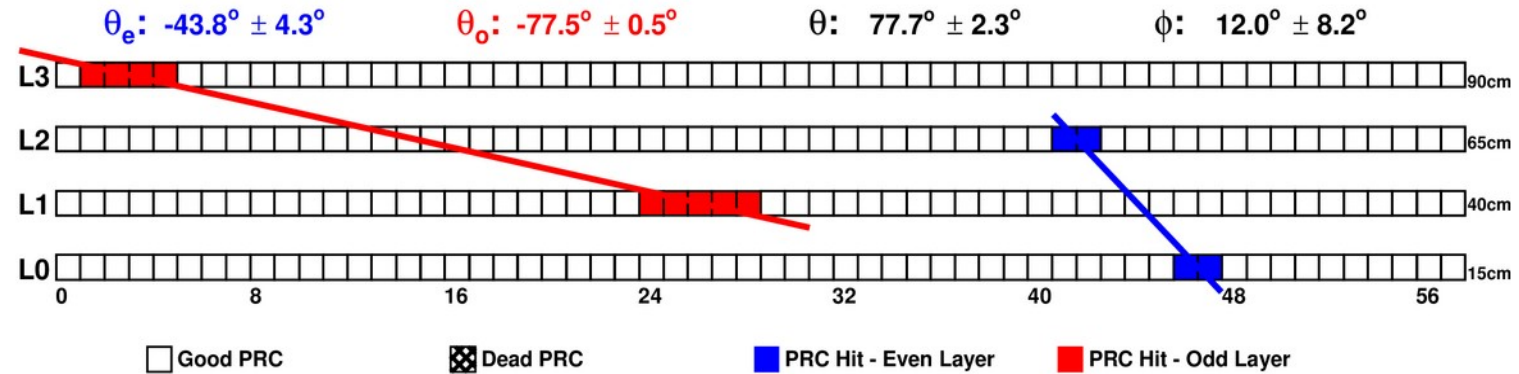


# The new triggerless DAQ

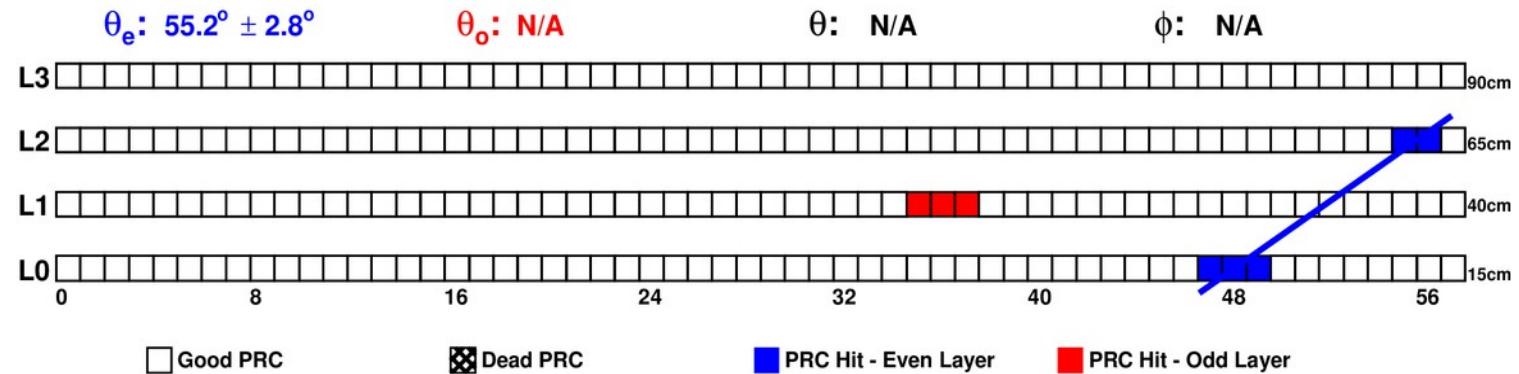
- ALICE FPGA card
- Onboard 100 MHz and 50 MHz clock
- Time resolution 10 ns
- Pulse width-time and count rate monitoring
- I/P signal rate ~60 kHz
- O/P data rate ~4 Mbps
- Dead time ~0.001%

# Large angle muons

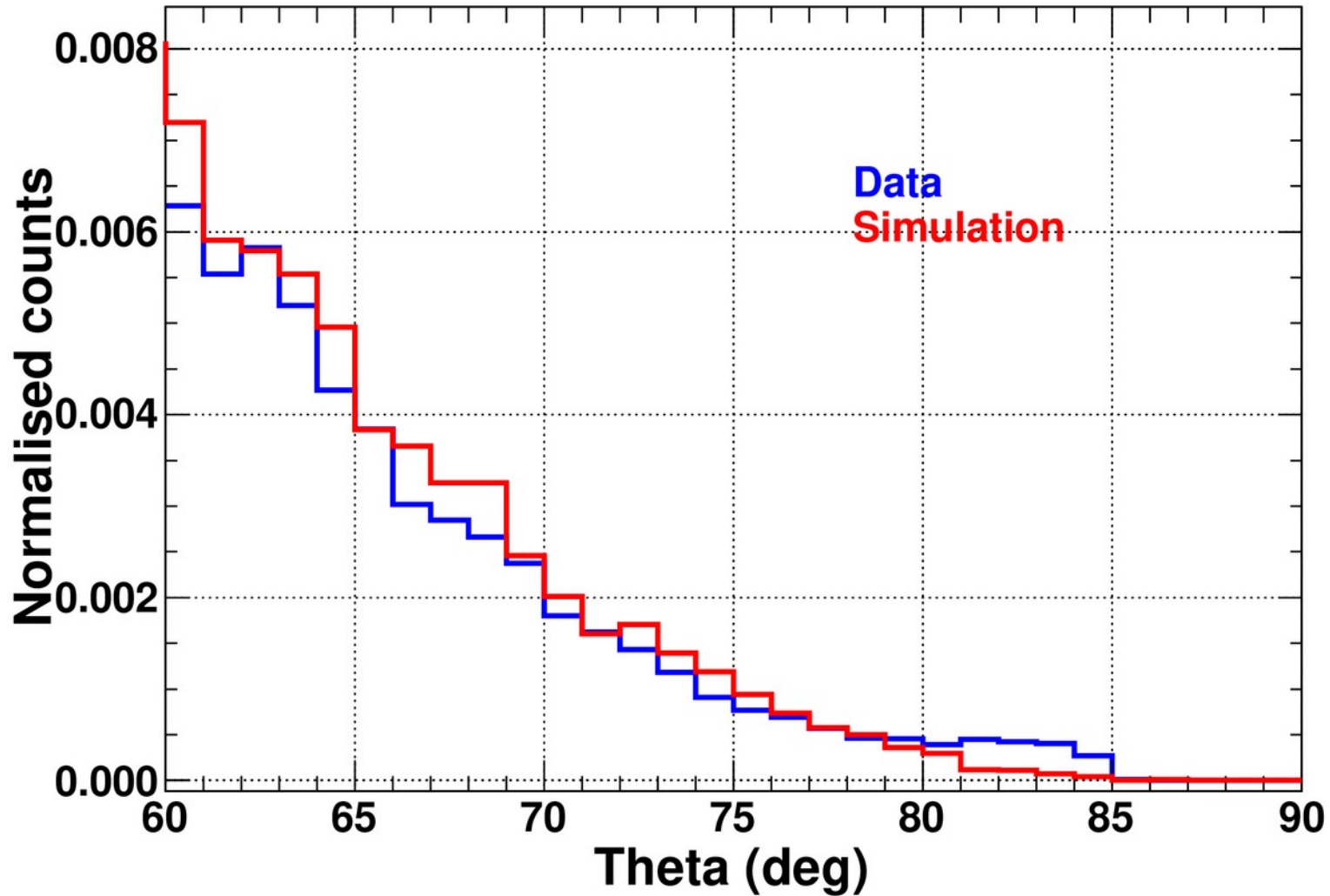
Date: 2021-03-24 Trig\_Time: 10:20:03:073:455 EAS\_Time: N/A Event: 424 No. of Hits: 13



Date: 2021-03-24 Trig\_Time: 10:20:14:458:338 EAS\_Time: N/A Event: 2591 No. of Hits: 8



# Zenith distribution

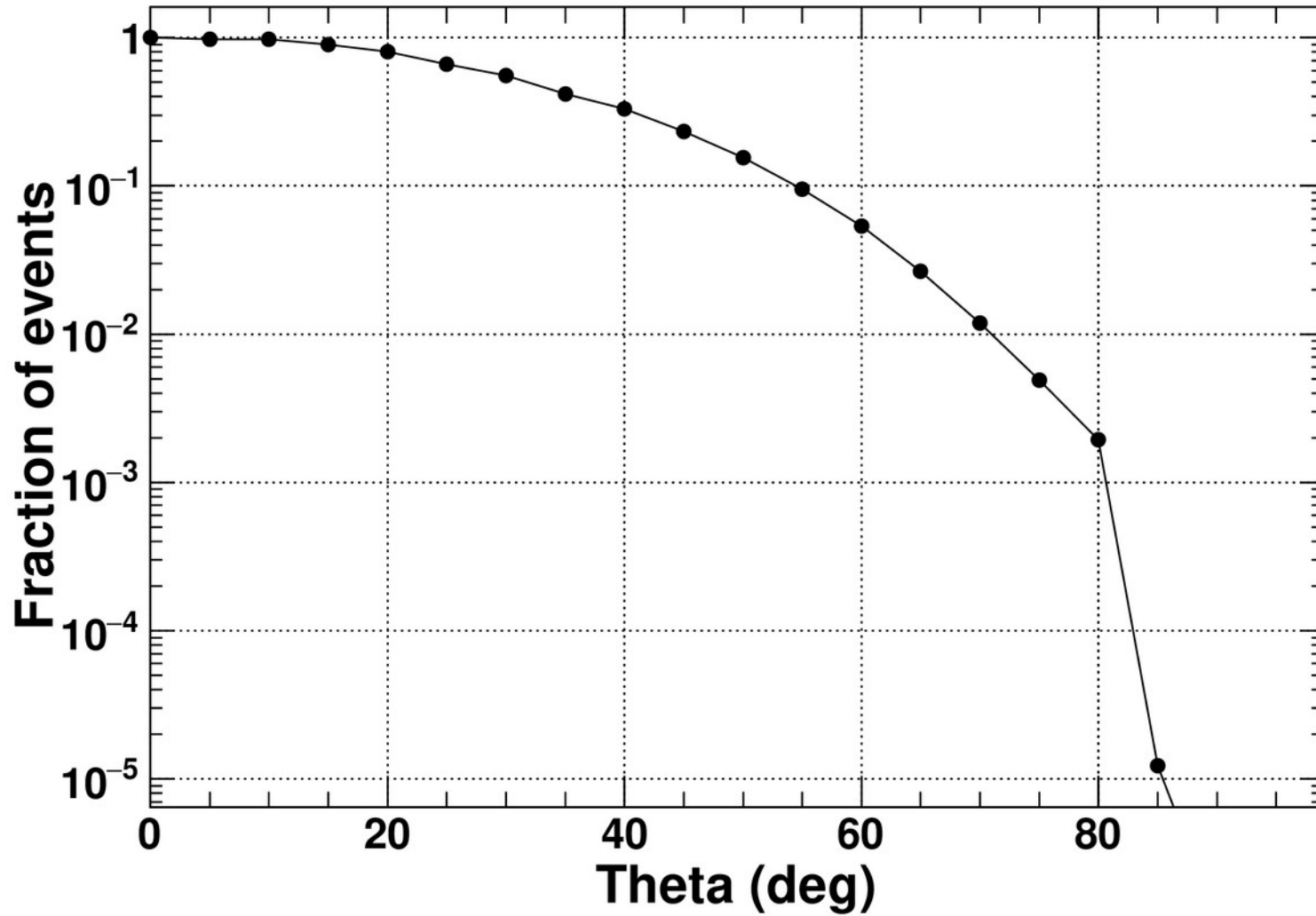


Data: 4-fold and  $\theta > 60^\circ$

MC: CORSIKA v76900

Proton,  $10^{10} - 10^{12}$  eV,  $0 \leq \theta \leq 85^\circ$

# Zenith distribution



Data: 4-fold and  $\theta > 60^\circ$

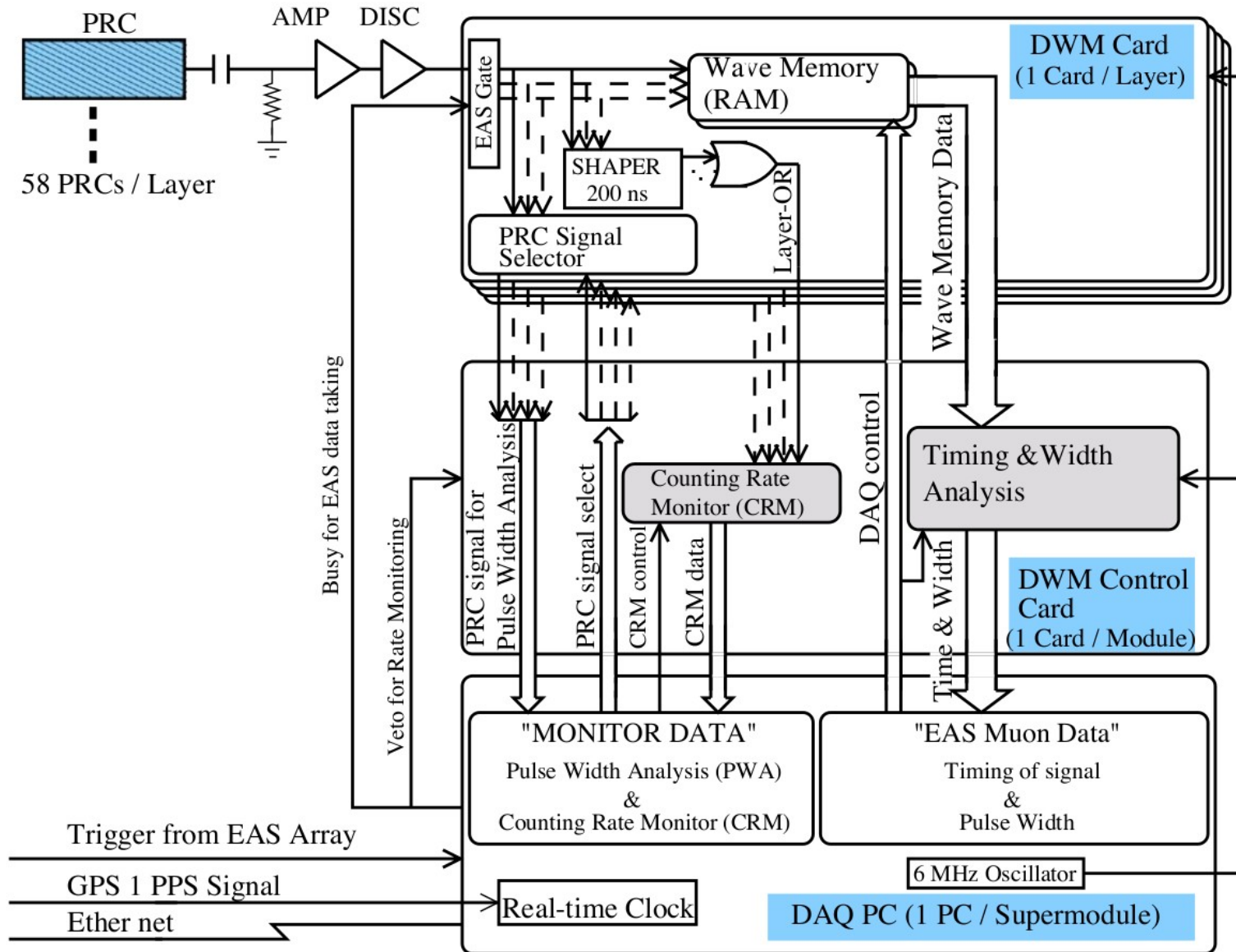


# Conclusions

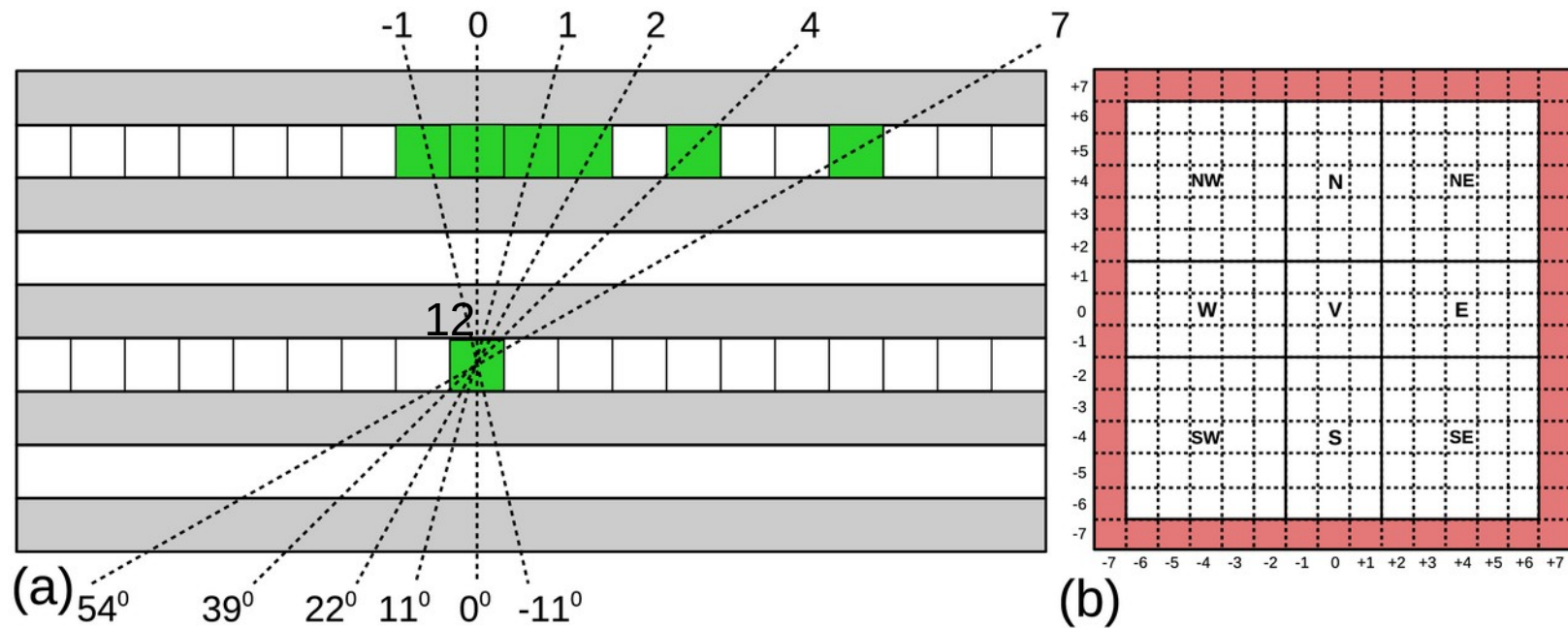
- DAQ designed to be triggerless
- Deployed for 25% of the telescopes
- Offline software trigger
- Ability to identify muons with timestamp (10 ns resolution)
- Large angle muons
- Extending the physics scope of the detector

Thank You

# Conventional DAQ



# Conventional way of direction reconstruction



# Direction reconstruction

- Preparation
  - Formation of normalised time using 100 MHz clock count
  - Sorting the PRC hits based on normalised time
- Identification of clusters
  - Successive hits (N) delay  $< 1.1 \mu\text{s}$
  - Minimum  $N = 2$
  - Trigger time:  $T = \text{last hit time}$  if  $N \leq 6$
  - $T = \text{middle hit time}$  if  $N > 6$

# Direction reconstruction

- Direction ( $\theta$ ,  $\phi$ ) determination
  - Identification of blocks in each layer
  - Blocks' coordinates are plotted and fitted for each projection (i.e. Even: L0 & L2, Odd: L1 & L3)
  - From the slopes ( $S$ ) of least square fitting

$$\theta_{e,o} = \arctan(S_{e,o})$$

$$\theta = \arctan(\sqrt{S_e^2 + S_o^2})$$

$$\phi = \arctan(S_o^2 / S_e^2)$$