

# Hardware Development for the Radio Neutrino Observatory in Greenland (RNO-G) Daniel Smith, on behalf of the RNO-G Collaboration, University of Chicago, danielsmith@uchicago.edu

## Introduction

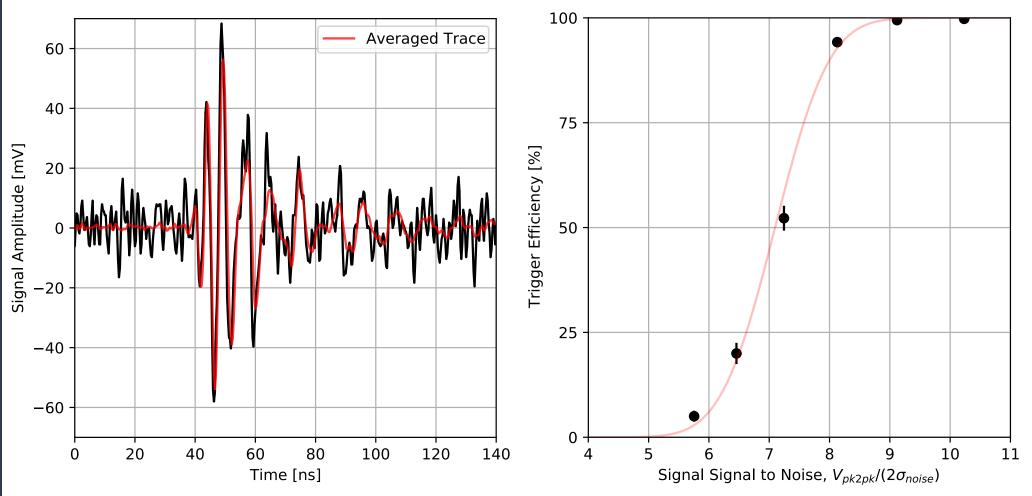
The Radio Neutrino Observatory in Greenland (RNO-G) is designed to make the first observations of ultra-high energy neutrinos at energies above 10 PeV and will be the world's largest in-ice Askaryan radio detection array. The experiment will be composed of 35 autonomous stations deployed over a 5x6 km grid near NSF Summit Station on top of the Greenland ice sheet. The first deployment is ongoing, with the first team arriving in May 2021.

#### Station Design

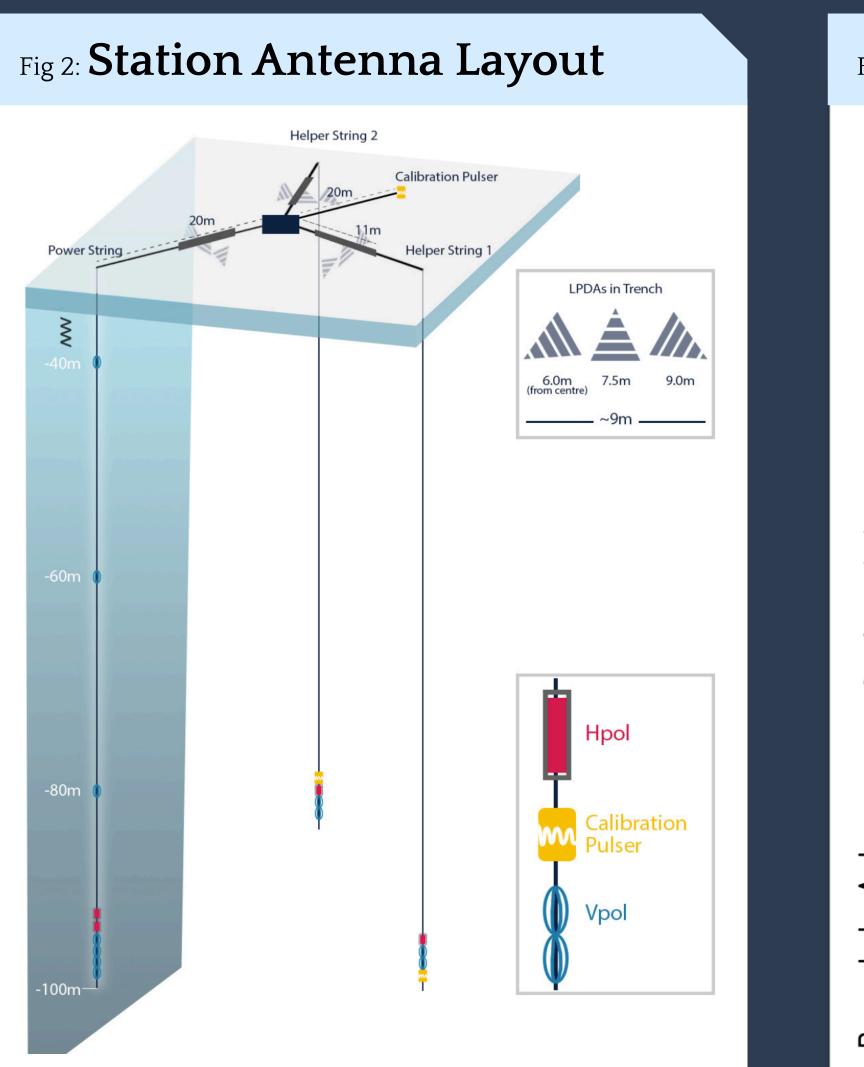
Each station is centered around the environmental enclosure, which contains the data acquisition system (DAQ), power controls, batteries, and single-board computer-based station controller. The primary sensing component are the antennas that are deployed down three, 100 m boreholes. The surface array of high-gain antennas is used for noise rejection, cosmic ray tagging and improved reconstruction. Station power is composed of a battery bank and solar panels. Wireless communications is performed over a LoRaWAN and LTE network.

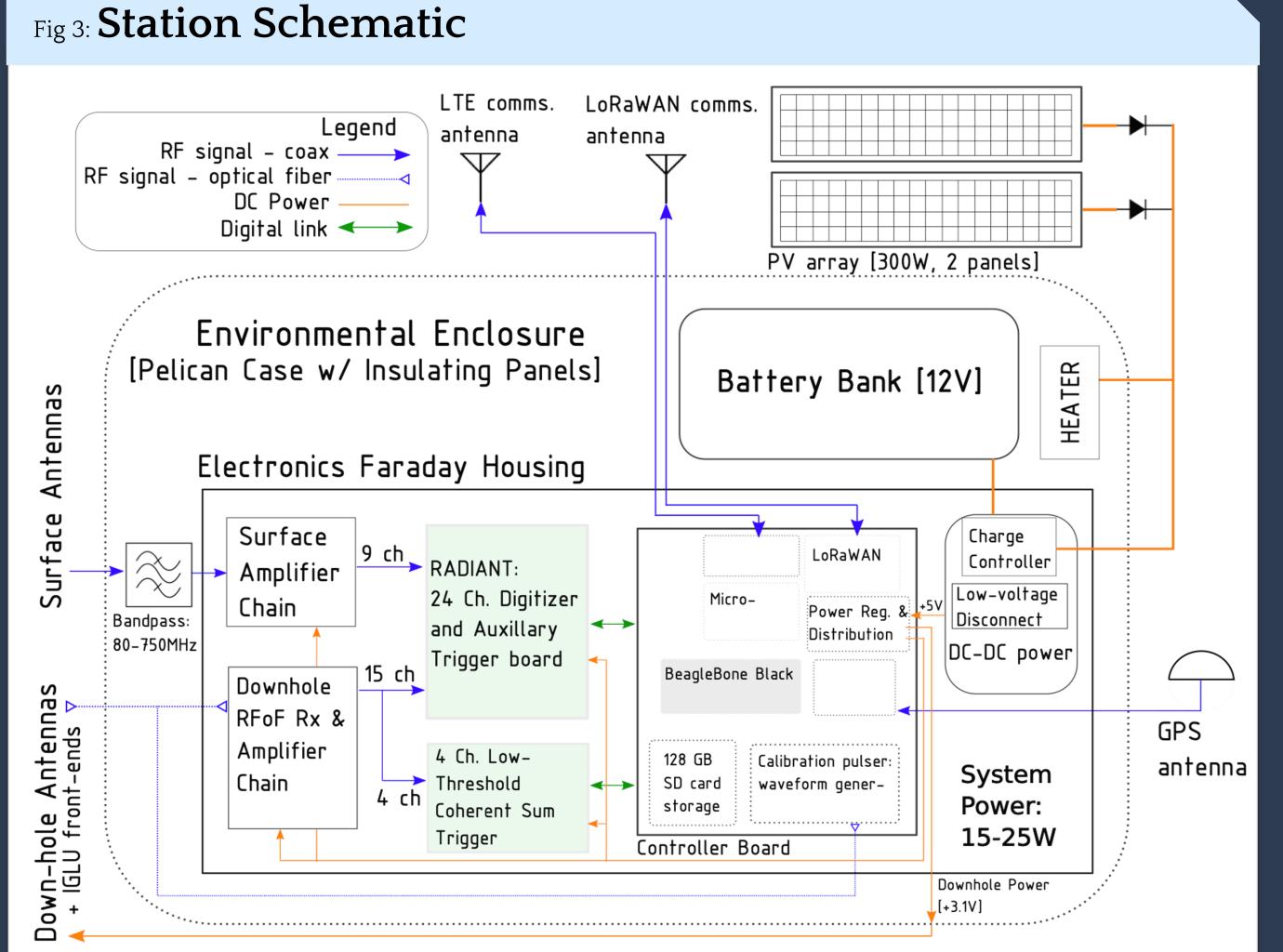
### Digitizer and Triggering

Signal digitizing is performed on a custom, 24 channel board based on the LAB4D, a custom ASIC that is a single channel, switched-capacitor array with 12-bit sampling [2]. The board is optimized for low power and runs at approximately 12.5 W. Surface triggering is performed using a Schottky diode detector circuit (a threshold trigger on an enveloped signal) that is deployed alongside each channel on the digitizing board. Deep triggering is performed using a four channel, 100-250 MHz phased array trigger implemented on a dedicated FPGA [3].



**Fig 1: Left**: 100–225 MHz pulse through signal chain and digitized by LAB4Ds. Right: Preliminary trigger efficiency of surface antennas on 100–225 MHz pulse.





### Fig 4: Antennas & Simulations

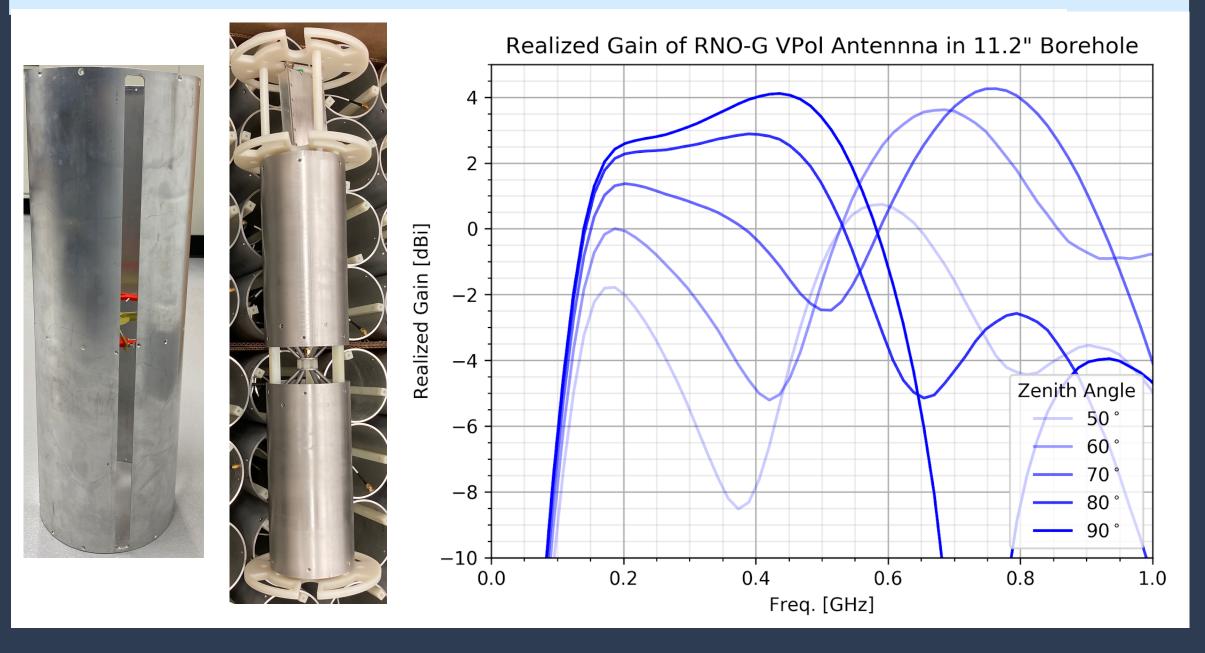


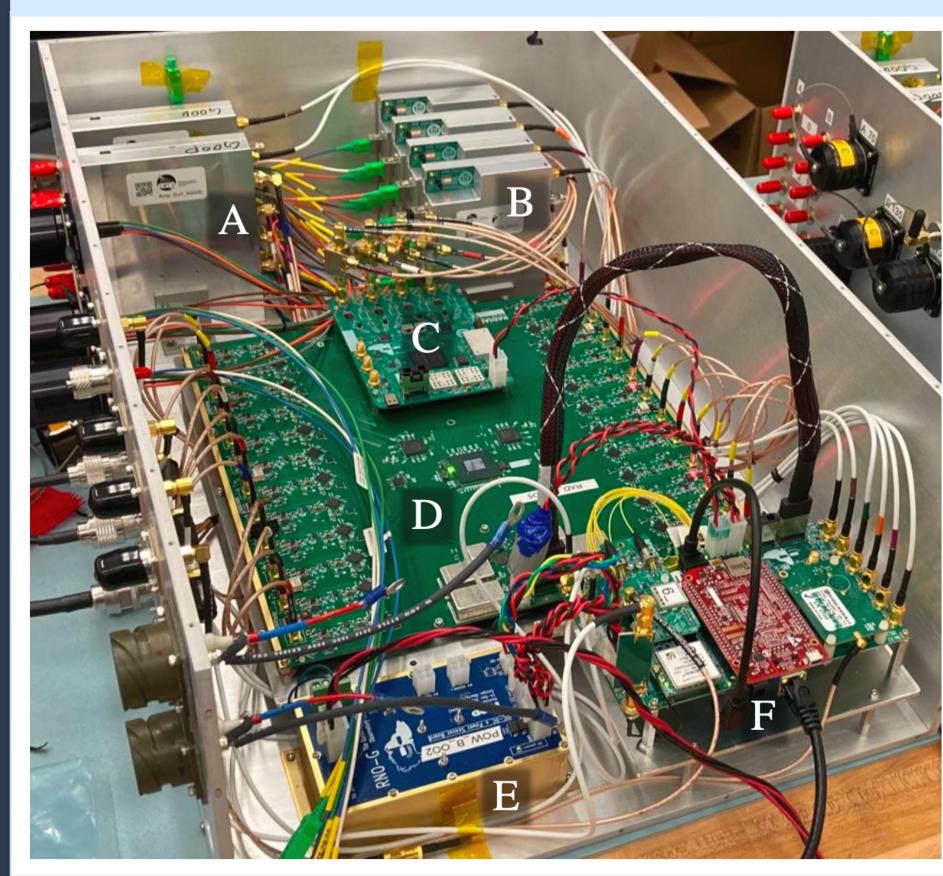
Fig 2: Station antenna layout, including surface & deep antennas and calibration pulsers Fig 3: Station schematic, outlining all subsystems of a single station.

**Fig 4**: HPol (left) and VPol (middle) antennas with Vpol simulated antenna gain (right)

Fig 5: Assembled DAQ box, including (a) Surface amplifiers, (b) Deep amplifiers,

(c) low threshold trigger board, (d) digitizer board, (e) power regulator, and (f) controller board.

### Fig 5: Assembled DAQ



#### Antenna Design

Surface antennas, unconstrained by geometry, are commercially available, high-gain log-periodic dipole antennas. Deep antennas must operate within the 11.2" diameter ice borehole. The custom verticallypolarized (Vpol) antennas are fat-dipoles and the custom horizontallypolarized (Hpol) antennas are quadslot antennas. Simulations are nontrivial due to the ice far-field and an ice / air interface from the borehole that is in the antenna near field. In-situ calibrations are forthcoming.





#### Deployment

Deployment is ongoing, with the first drilling and science team arriving at Summit Station in May 2021. To date, on-base infrastructure has been constructed (including the LTE network, LoRAWAN network, station data server and off-station telemetry), borehole drilling continues, and the first station has been deployed. Further station deployments will continue over the season and extensive in-situ calibration will be performed in August 2021. Deployments in Summer 2022 and 2023 are scheduled to complete the 35 station array.

Fig 6: Top: DAQ box assembly line Left: Completed borehole. Middle: Ice drill ejecting chips Right: All assembled vertically polarized antennas

#### **References and Acknowledgements**

[1] RNO-G Collab., J. A. Aguilar et al. JINST 16 no. 03, (2021) P03025 [2] M. Roberts et al. Nucl. Instrum. Meth. A 925 (2019) 92–100. [3] P. Allison *et al.* Nucl. Instrum. Meth. A 930 (2019) 112–125.



